2.8” QVGA 262k TFT LCD module with Touch Panel integrated
INTRODUCTION

The part number TY280T_230320_BO (Board Rev 1B) is a development board for 2.8” QVGA TFT-LCD module completed with a 32MBx8bit NAND Flash, 74HC573D latch device, white LED backlight driver circuit, and a 4-wire touch screen controller all soldered onboard. Standardized 2.54mm PCB sockets have been included for sake of easy prototype procedure. Below please find an illustration of all components in details.
### FEATURES OF THE LCD MODULE

<table>
<thead>
<tr>
<th>ITEM</th>
<th>STANDARD VALUE</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>LCD Type</td>
<td>2.8” QVGA TFT-LCD</td>
<td>-</td>
</tr>
<tr>
<td>Backlight</td>
<td>4 White LEDs in parallel</td>
<td>-</td>
</tr>
<tr>
<td>Module size</td>
<td>50.0(W) x 69.2(H) x 4.2(T) (with Touch Panel TP)</td>
<td>mm</td>
</tr>
<tr>
<td>TP viewing area</td>
<td>44.80 (W) x 63.10 (H)</td>
<td>mm</td>
</tr>
<tr>
<td>TP active area</td>
<td>44.20 (W) x 62.50 (H)</td>
<td>mm</td>
</tr>
<tr>
<td>LCD active area</td>
<td>43.20 (W) x 57.60 (H)</td>
<td>mm</td>
</tr>
<tr>
<td>Dot number</td>
<td>240 (RGB) x 320</td>
<td>-</td>
</tr>
<tr>
<td>Pixel pitch</td>
<td>0.18(h) x 0.18(v)</td>
<td>mm</td>
</tr>
<tr>
<td>Operation temperature</td>
<td>-10 ~ 70</td>
<td>°C</td>
</tr>
<tr>
<td>Storage temperature</td>
<td>-30 ~ 80</td>
<td>°C</td>
</tr>
<tr>
<td>Driver IC</td>
<td>ILI9325</td>
<td>-</td>
</tr>
<tr>
<td>Interface mode</td>
<td>8080 system 16 bit interface</td>
<td>-</td>
</tr>
<tr>
<td>Color mode</td>
<td>262k / 65k software control</td>
<td>-</td>
</tr>
</tbody>
</table>

### ELECTRICAL CHARACTERISTICS

<table>
<thead>
<tr>
<th>ITEM</th>
<th>SYMBOL</th>
<th>CONDITION</th>
<th>MIN.</th>
<th>TYP.</th>
<th>MAX.</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply Voltage</td>
<td>VDD</td>
<td>Logic</td>
<td>2.9</td>
<td>3.0</td>
<td>3.4</td>
<td>V</td>
</tr>
<tr>
<td>Input Voltage</td>
<td>Vih</td>
<td>H level</td>
<td>0.7</td>
<td>VDD</td>
<td></td>
<td>V</td>
</tr>
<tr>
<td></td>
<td>vIL</td>
<td>L level</td>
<td>0</td>
<td>0.3VDD</td>
<td>0.3VDD</td>
<td>V</td>
</tr>
<tr>
<td>Current Consumption</td>
<td>IDD</td>
<td>With internal voltage generation</td>
<td>--</td>
<td>--</td>
<td>20</td>
<td>mA</td>
</tr>
</tbody>
</table>

### MAXIMUM RATINGS

<table>
<thead>
<tr>
<th>ITEM</th>
<th>SYMBOL</th>
<th>MIN.</th>
<th>MAX.</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply Voltage</td>
<td>VDD</td>
<td>-0.4</td>
<td>4.0</td>
<td>V</td>
</tr>
<tr>
<td>Input Voltage</td>
<td>VIN</td>
<td>-0.4</td>
<td>VDD+0.4</td>
<td>V</td>
</tr>
<tr>
<td>Operating temperature</td>
<td>TOPR</td>
<td>-20</td>
<td>70</td>
<td>°C</td>
</tr>
<tr>
<td>Storage temperature</td>
<td>TSTR</td>
<td>-30</td>
<td>80</td>
<td>°C</td>
</tr>
<tr>
<td>Humidity</td>
<td>--</td>
<td>--</td>
<td>90</td>
<td>%RH</td>
</tr>
</tbody>
</table>

*Remarks: data for the bare LCD module only.

### BACKLIGHT CHARACTERISTIC

<table>
<thead>
<tr>
<th>ITEM</th>
<th>SYMBOL</th>
<th>MIN.</th>
<th>TYPICAL</th>
<th>MAX.</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>LED module Forward voltage</td>
<td>VLED</td>
<td>3.0</td>
<td>--</td>
<td>3.4</td>
<td>V</td>
</tr>
<tr>
<td>LED module current</td>
<td>ILED</td>
<td>--</td>
<td>80</td>
<td>--</td>
<td>mA</td>
</tr>
<tr>
<td>L/G Surface Luminance</td>
<td>Ls</td>
<td>3200</td>
<td>--</td>
<td>4500</td>
<td>Cd/m²</td>
</tr>
<tr>
<td>LCM Surface brightness</td>
<td>LD</td>
<td>80</td>
<td>--</td>
<td>--</td>
<td>%</td>
</tr>
</tbody>
</table>
Please refer to our web site at


for schematic of the breakout board. Besides the LCD module, there are several components of interest:

1. LED backlight circuit driven by On Semiconductor® NCP5604A
2. 32MB*8bit NAND Flash from Hynix Semiconductor®. This IC is useful for mass data storage such as jpeg or bitmap files. This is no stranger! Normally this chip is found in Thumb Drives today. Dedicated USB thumb drive controllers are used with firmware for low level USB connection, nandFlash driver as well as the USB Mass Storage Device firmware in a single controller chip (OTI as shown on the picture below).

3. Touch Panel controller ADS7846E from Texas Instrument®. This controller is optional because it is possible to interface directly the resistive wires to AD converters of a microcontroller. An example has been provided by Microchip GUI library. Demonstration program is available from our web site with port for Microchip Library using the Touch Panel. However, it is just in case that you do not want to use the Microchip library, ADS7846E is a nice device to play with. Please make sure JP2 – JP5 pads would be shunt to enable the controller. You need to apply solder a bit to these pads to complete the bridges joining XR, XL, YU, YD wires to ADS7846’s inputs.
4. 3-State Octal latch 74HC573D for data IO. It is because the LCD module uses 16-bit addressing, we need a data latch to extend the bus width from 8-bit to 16-bit if we are using a low-end 8-bit microcontroller. A good example is PIC18LF4550 with embedded USB port. However, if there are enough data lines from the microcontroller, it is always advisable to use 16-bit addressing for higher efficiency. What we need is just to make sure JP6 jumper is not connected to disable the latch (high impedance output). In this case, we may use a complete 16-bit port to drive LCD module. Referring to block diagram on next page, it could be a microcontroller’s PORT[0:15] directly interface DB[0:15] of the module.
**BLOCK DIAGRAM**

**Microcontroller**

- PORT A
- PORT B
- GPIO
- AD Converter
- SPI Port
- NCP5604A
- ADS7846E

**NAND Flash**

- Control signals: RS, WR, RD etc.
- DB0 - DB15
- DB0 - DB7

**4-wires resistive touch panel network**

**LCD Module**

- 74HC573D
- 4-wires NAND FLASH

**Microcontroller**

- PORT A
- PORT B
- GPIO
- GPIO
- AD Converter
- SPI Port
- NCP5604A
- ADS7846E

**NAND Flash**

- Control signals: RS, WR, RD etc.
- DB0 - DB15
- DB0 - DB7

**4-wires resistive touch panel network**

**LCD Module**

- 74HC573D
- 4-wires NAND FLASH
SOFTWARE : Microchip Graphics Display Solution

There are a number of GUI libraries known to the author. To name a few of those:

2. emWin supplied by Segger Microcontroller GmbH & Co. KG (www.segger.com)
3. Graphical User Interface (GUI) libraries by RAMTEX International (www.ramtex.dk)
4. µC/GUI by Micrium (www.micrium.com)
5. wxWidgets (http://www.wxwidgets.org/)

All of them focus on GUI libraries for embedded systems with charges. The last item being the wxWidget is an open source GUI; however, it seems not for small embedded systems as it requires C++ and powerful processor and OS like Windows CE.

The author is deeply surprised by the strategy of Microchip that a full-blown Graphical User Interface (GUI) library is provided free with source code. One may find its relevant information from Microchip web site at


Web seminars and application notes are available for download at no cost and a Free Licensed Microchip Graphic Library with schematics, drivers, documentation, and utilities also there as long as you are using this GUI on Microchip products. Normally such drivers and support would be sold at a certain cost, sometimes rather expensive too. Now we may use this library with only minor modification. This manual describes the procedure to port a new driver IC to the Microchip Graphic Library.

PROCEDURE

The first step is to download a copy of the Microchip Graphics Library. The current version at time of writing is v1.4. After download and installation, one would get a new folder under C:\Microchip Solutions if the default configurations have been accepted. Under Windows Explorer, browse to All Programs\Microchip\Microchip Graphics Library v1.4 you will see all documentations in pdf and a help file. Full detail of the library has been provided under the Microchip Graphics Library Help (html help) and we hereby follow its instruction to port a new LCD driver for our 2.8” LCD module.
LIBRARY STRUCTURE

There are hundreds of LCD driver-ICs in the world. At time of writing only the following driver-ICs are supported by the original Graphics Library. They are located under ..\Microchip Solutions\Microchip\Graphics for *.c driver and ..\Microchip Solutions\Microchip\Include\Graphics for *.h header

<table>
<thead>
<tr>
<th>Driver IC</th>
<th>Orientation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Densitron HIT1270L</td>
<td>Landscape</td>
</tr>
<tr>
<td>LG LGDP4531</td>
<td>Landscape / portrait</td>
</tr>
<tr>
<td>Renesas R61505</td>
<td>Landscape / portrait</td>
</tr>
<tr>
<td>Samsung S6D0129 / S6D0139</td>
<td>Landscape / portrait</td>
</tr>
<tr>
<td>Sino Wealth SH1101A OLED</td>
<td>Landscape</td>
</tr>
<tr>
<td>Orise SPFD5408</td>
<td>Landscape / portrait</td>
</tr>
<tr>
<td>Solomon Sys Tech SSD1339 OLED</td>
<td>128*128 matrix</td>
</tr>
<tr>
<td>Solomon Sys Tech SSD1906</td>
<td>Landscape / portrait</td>
</tr>
<tr>
<td>Solomon Sys Tech SSD1303</td>
<td>Landscape</td>
</tr>
</tbody>
</table>

If we are going to use the library with a third-party LCD module, we need to port the graphics library to our target driver IC. Thanks to the modular design, we only need to deal with the low-level I/O layer for ILI9325.

Navigate to Library Structure under Contents of the Help file we learn the library architecture. We only need to deal with the Device Specific layer and there are three files involved.

They are
..\Microchip\Graphics\device.c
..\Microchip\Include\Graphics\device.h
..\Microchip\Include\Graphics\Graphics.h
PRIMITIVE DEMO

In our case, device.c and device.h become ILI9325P_16BIT.c and ILI9325P_16BIT.h with indication of the driver IC, portrait orientation denoted as "P", and it is a 16 bit driver. There are several steps involved to start a new project with Microchip Graphics Library of course. One may refer to the help.html file again and navigate to Miscellaneous Topics → Starting a New Project to learn all relevant procedures to create a fresh project from scratch. Else, one may also consider downloading our fully-built example to get a kick-start with the Primitive Demo. This demonstration program is based on the hardware platform (part no: PIC24-Eval-B2 Rev B) for PIC24FJ128GA010 microcontroller. Let’s take a look at the wiring for development board PIC24-Eval-1B.

### Relevant hyperlinks:

- www.techtoys.com.hk/Displays/TY280T240320/TY280T_240320_BO.htm under Doc 09

![Wiring Diagram]

### PIC24FJ128GA010

<table>
<thead>
<tr>
<th>PMD[7:0]</th>
<th>PMA[7:0]</th>
<th>RA7</th>
<th>PMA8</th>
<th>RD12</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
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</table>

### TFT color LCD module

<table>
<thead>
<tr>
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</thead>
<tbody>
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</table>

<table>
<thead>
<tr>
<th>PMPRD</th>
<th>PMPWR</th>
<th>RD10</th>
<th>RD13</th>
<th>RD12</th>
<th>RD11</th>
<th>RD1</th>
<th>3.3V</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>YD</th>
<th>XL</th>
<th>YU</th>
<th>XR</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>EN pin of NCP5604A (for backlight)</th>
<th>VDD</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Relevant hyperlinks:

- www.techtoys.com.hk/Displays/TY280T240320/TY280T_240320_BO.htm under Doc 09

![Wiring Diagram]
TOUCH PANEL DEMO (AN1136)

This example was modified from the source code for the application note AN1136 released by Microchip. This note discusses the know-how to use Widgets in Microchip Graphics Library. A port for our 2.8” TFT LCD has been finished with full source code available from the following hyperlink.


Location of AN1136 is available at http://www.microchip.com/stellent/idcplg?IdcService=SS_GET_PAGE&nodeId=2608&param=en532067

In Touch Panel demo, we need to emphasize RB10, RB13, RB12, and RB11 with an interface to YD (Y Down), XL (X left), YU (Y Up), and XR (X Right) respectively.

<table>
<thead>
<tr>
<th>PIC24FJ128GA010</th>
<th>TFT color LCD module</th>
</tr>
</thead>
<tbody>
<tr>
<td>PMD[7:0]</td>
<td>DB[7:0]</td>
</tr>
<tr>
<td>PMA[7:0]</td>
<td>DB[15:8]</td>
</tr>
<tr>
<td>RA7</td>
<td>RESET (/RES)</td>
</tr>
<tr>
<td>PMA8</td>
<td>Data or Command (RS)</td>
</tr>
<tr>
<td>RD12</td>
<td>Chip select (/CS)</td>
</tr>
<tr>
<td>PMPRD</td>
<td>Read enable (/RD)</td>
</tr>
<tr>
<td>PMPWR</td>
<td>Write enable (/WR)</td>
</tr>
<tr>
<td>RB10</td>
<td>YD</td>
</tr>
<tr>
<td>RB13</td>
<td>XL</td>
</tr>
<tr>
<td>RB12</td>
<td>YU</td>
</tr>
<tr>
<td>RB11</td>
<td>XR</td>
</tr>
<tr>
<td>RD1</td>
<td>EN pin of NCP5604A (for backlight)</td>
</tr>
<tr>
<td>3.3V</td>
<td>VDD</td>
</tr>
</tbody>
</table>

A better illustration is repeated by the block diagram next page with focus on the Touch Panel portion.
We have two choices to decode the Touch Panel signal:
1. Use internal Analog-to-Digital converter (ADC) of the PIC24 microcontroller
2. Use the external ADS7846E Touch Panel driver onboard by manually shunt jumpers JP2 to JP5.

Since we are using the Microchip library for now, the first option has been used. Two files TouchScreen.h and TouchScreen.c take care of the decode task. A real-life demo by running the program is shown below. One may use finger or stylus for touch panel action.

The file TouchScreen.h provides definitions for ADC channels plus a few necessary calibration constants such as YMINCAL and YMAXCAL. If you need to modify the source code for your particular hardware, you need to change the definitions:

```c
#define ADC_XPOS 13
#define ADC_YPOS 12
```

as well as X and Y port definitions on next page.
// Y port definitions
#define ADPCFG_XPOS AD1PCFGbits.PCFG13
#define ADPCFG_XNEG AD1PCFGbits.PCFG11
#define LAT_XPOS LATBbits.LATB13
#define LAT_XNEG LATBbits.LATB11
#define TRIS_XPOS TRISBbits.TRISB13
#define TRIS_XNEG TRISBbits.TRISB11

// X port definitions
#define ADPCFG_YPOS AD1PCFGbits.PCFG12
#define ADPCFG_YNEG AD1PCFGbits.PCFG10
#define LAT_YPOS LATBbits.LATB12
#define LAT_YNEG LATBbits.LATB10
#define TRIS_YPOS TRISBbits.TRISB12
#define TRIS_YNEG TRISBbits.TRISB10

We may illustrate the wiring diagram below if we view the LCD module in the landscape direction. Please note that this diagram is true only for the hardware platform PIC24-Eval-B2 Rev B evaluation board + TY280T-240320-BO Rev 1B LCD module.
A resistive touch panel is composed of several layers. The most important are two thin metallic electrically conductive and resistive layers separated by thin space. When the panel is touched at a certain position, the layers are connected at that point. The panel then acts similar to two voltage dividers with connected outputs.

The touch position may be calculated by the following equations.

\[
\text{Voltage in the X direction} = \frac{R_2x}{R_1x + R_2x} \times \text{Full voltage range}
\]

\[
\text{Voltage in the Y direction} = \frac{R_1y}{R_1y + R_2y} \times \text{Full voltage range}
\]

These two equations provide just a simplified model. The actual implementation is a lot more complicated than this. First, one needs to make sure the panel would be sampled frequent enough so that there is no valid touch action to miss. This is the purpose of timer interrupt \_\_T3Interrupt(void) in TouchScreen.c. The period of Timer3 interrupt is defined under the function TouchInit(void) as TOUCH_DELAY_PRESS, which in turns has been defined as 1800/DEBOUNCE (1800/2=900). This provides a sampling period of approximately 450µsec. A state machine is defined in Timer3 interrupt function. First RB12 and RB10 would be "energized" to Vcc and ground to provide a voltage source for the potential divider in x-direction. Then, RB13 will be sampled for ADC input. If it is not a “no-touch” result and two conversions are equal, this is considered to be a valid touch action and the sequence will be swapped for a measurement in the y-direction (one should refer to the source code under \_\_attribute\_\_ADC1Interrupt(void) for details).

Because every touch panel has its intrinsic resistance, the values for XMINCAL, YMAXCAL, XMINCAL, XMAXCAL, and CAL_DELTA (namely default calibration values) would be different. These constants are defined under the file TouchScreen.h and they are important for telling if the Touch panel has been touched or not. Therefore it is advised to calibrate for their variation prior to usage. One may read from the source code under \_\_ADC1Interrupt(void) to note that the default calibration values do play an important role of how the program flow.
void __attribute__((interrupt, shadow, auto_psv)) _ADC1Interrupt(void)
{
    static SHORT prevRes = -1;
    static SHORT tempX;
    SHORT res;

    res = ADC1BUF0;

    switch(state){
    case SET_X_CHANNEL:
        break;
    
    case MEASURE_X:
        // Check if screen is not touched
        if( (res<(XMINCAL-CAL_DELTA)) ||  (res>(XMAXCAL+CAL_DELTA)) )
        {
            PR3 = TOUCH_DELAY_PRESS;
            res  = -1;
        }else{
            PR3 = TOUCH_DELAY_MOVE;
        }
    ...

Listing above shows an extract of the ADC routine. The testing condition for a no-touch is that, if the ADC result ‘res’ is smaller than the constants XMINCAL-CAL_DELTA or it is larger than XMAXCAL+CAL_DELTA, the variable ‘res’ will be assigned a value of -1 (0xFFFF) which implies no-touch.

Let’s magnify the panel. If one looks closely to the edge of the Touch Panel, you will find a gap between the panel edge and the LCD pixel area underneath. That means the highest value measured from XPOS when no-touch will be higher than the left-most calibration point, say.

\[
\begin{align*}
\text{RB12 (YPOS)} & = \text{Vcc} \\
\text{470k} & \\
\text{R}_{\text{gap-x}} & \\
\text{left-most calibration point} & \text{sampled by RB13(XPOS)}
\end{align*}
\]
One may find out the maximum and minimum calibration values by **holding KEY1** on PIC24-Eval-B2 board and **press RESET**. The following screen will be shown.

Touch screen to continue to bring up the next calibration screen. Try touching the top left corner to calibrate the panel. Calibration results will be stored in eeprom of PIC24 evaluation board after finishing all three calibration points at the top left, bottom left, and middle right. All goes smooth except when I changed the LCD module of a different specification. My experience is that, if $X_{MAXCAL}$ has been defined a value too low or $X_{MINCAL}$ too high; statements in the switch-case MEASURE_X will never measure a trigger at the top left, say.

ADC result measured at RB13 at top left

$$= Vcc - (Vcc \times \frac{R_{gap-x}}{R_x})$$

with $R_{gap-x}$ a finite value.

If we take noise into account, the ADC result is likely to fluctuate with numerous factors such as circuit design, PCB layout, power supply noise, etc. Suitable values of $X_{MAXCAL}$, $X_{MINCAL}$, $Y_{MINCAL}$, and $Y_{MAXCAL}$ may be measured by simple printf statements append right after successful ADC measurements in the function `TouchCalibration(void)`.

Connect a straight cable from J28 standard RS232 female connector to your PC's COM PORT. Start Docklight ([www.docklight.de](http://www.docklight.de)) or HyperTerminal Program and adjust the baud rate to 19200bps, 8-n-1 to record the calibration values. Restart the calibration procedure by holding KEY1 and press RESET. A screen shot similar to that on next page will be shown.
Screen shot of Docklight reflects several issues:

1. MAX ADC_XPOS value measured at XPOS when YPOS=Vcc, YNEG=GND, and no touch. This value fluctuated with a range from 0x3E9 to 0x3FD. The theoretical max 10-bit ADC result is 0x3FF so this is pretty close to it.

2. MAX ADC_YPOS value measured at YPOS when XPOS=Vcc, XNEG=GND, and no touch. This value fluctuated more than XPOS though the program flow is basically the same as case 1, except a simple swap between the measurement points. It ranges from a rather low value 0x31F to 0x3FF.

3. _calXMMax when the Touch Panel was calibrated at the top left corner of the active LCD area. It recorded two instances of 0x394 and one instance of 0x39F. The max value (i.e. 0x39F) would be selected and saved in eeprom for position calculation later. This value is less than the least MAX ADC_XPOS value (0x3E9). Basically if we make a decision that, once the measured result ‘res’ is larger than 0x39F, the touch point would be considered off-screen for XPOS. This translates to the following syntax.

```c
#define XMAXCAL 0x39F
...  
if (res>XMAXCAL) res = -1;
...  
```

The original source code didn’t include any comment about why a CAL_DELTA factor should be summed to XMAXCAL, nor why CAL_DELTA should be 0x60 in the original code. The author’s feeling is that these are intrinsic properties of a Touch Panel. Every manufacturer may have different series of the same Touch Panel model number but the resistance may vary. In addition, a different circuit design and PCB layout is also playing important role since we are doing ADC on a digital
circuit. By trail-an-error, a value of CAL_DELTA=0x30 instead of 0x60 has been used for 2.8” TFT LCD which seems fairly stable.

\[ X_{\text{MAXCAL}} + \text{CAL\_DELTA} \]
= \[0x39F + 0x30\]
= \[0x3CF\]

Once again, if ‘X_{\text{MAXCAL}} + \text{CAL\_DELTA}’ has been assigned a value too low; ADC result ‘res’ will always be higher than \[X_{\text{MAXCAL}} + \text{CAL\_DELTA}\] leading to no response from the top left corner during the calibration procedure. On the other hand, if this is set a value too high (or simply 0x3FF), the variable ‘res’ will always be smaller even when there is no touch action leading to false trigger.

4. _calYMin when the Touch Panel was calibrated at the top left corner. It recorded all three instances of 0x97. This value is going to be YMINCAL.

5. _calYMax when the Touch Panel was calibrated at the lower left corner. Similarly a maximum value of 0x32A has been recorded. However, ADC_YPOS was found to be much nosier than ADC_XPOS with a range from 0x31F to 0x3FF. With \[Y_{\text{MAXCAL}} = 0x32A\] and a \text{CAL\_DELTA} of 0x30, there will be false trigger when the Touch Panel was not even touched at all. Fortunately, noise screening algorithm such than 2 consecutive measurements and a successful record for adcX values is required prior to adcY to avoid mistake.

6. _calXMin when the Touch Panel was calibrated at the right middle edge of the active LCD area. A value of 0x7E assigned to XMINCAL.

By finishing the calibration, one may continue and experience the modified program from us for button and slide-bar widgets, and a simple demo for nandFlash read/write.
TOUCH PANEL DEMO FOR A 3.5” PANEL

So, what to do if there is a new hardware? A new product is being developed with 3.5” LCD module with external image processor. Now, this new LCD module has Touch Panel built-in without funny icons like the 2.8” LCD. Its aspect ratio and intrinsic resistance are different as well. The schematic is also different. The connection with ADC channels when it is stacked on PIC24 Evaluation board is shown below.

In order to keep XPOS and YPOS to the same edges at bottom and left, the following definition has been adapted in the header TouchScreen.h.

```c
#define ADC_XPOS        10
#define ADC_YPOS        13
...

// Y port definitions
#define ADPCFG_XPOS     AD1PCFGbits.PCFG10
#define ADPCFG_XNEG     AD1PCFGbits.PCFG12
#define LAT_XPOS        LATBbits.LATB10
#define LAT_XNEG        LATBbits.LATB12
#define TRIS_XPOS       TRISBbits.TRISB10
#define TRIS_XNEG       TRISBbits.TRISB12

// X port definitions
#define ADPCFG_YPOS     AD1PCFGbits.PCFG13
#define ADPCFG_YNEG     AD1PCFGbits.PCFG11
#define LAT_YPOS        LATBbits.LATB13
#define LAT_YNEG        LATBbits.LATB11
#define TRIS_YPOS       TRISBbits.TRISB13
#define TRIS_YNEG       TRISBbits.TRISB11
```
By the same calibration procedure described in last section, the following result has been found. It seems even though it is a larger screen with totally different intrinsic resistance, the calibration constants do not vary a lot. After finishing the calibration, the Touch Panel was tested showing fast and crisp responses.